PM Electric Power Steering Controller

Model 1220E
Model 1220E

The Curtis Model 1220E is a brushed DC permanent magnet motor controller for electric power steering and steer-by-wire systems. It fully meets the EN1175 1:1998+A1: 2010 standards. This controller is exclusively designed for Curtis Vehicle Control Language (VCL) enabled AC-traction controllers. The steering motor functions as an actuator to change the angle of the wheels thereby changing travel direction. Model 1220E interprets the steering command input and wheel position feedback, to steer the vehicle. Intended applications are class-3 material handling vehicles such as pallet trucks, stackers and similar industrial vehicles.

FEATURES

▶ Absolute and Relative position control modes.
▶ 20 kHz Pulse Width Modulation (PWM) switching frequency ensures silent operation.
▶ Advanced PWM techniques produce low motor harmonics, low torque ripple, and minimized heating losses, resulting in high efficiency.
▶ Configurable homing methods, center offset, and end-stop protection.
▶ 24V and 36/48V nominal supply voltage.
▶ 60A 1-minute current rating.
▶ Integrated hour meter and diagnostic log functions.
▶ Curtis 840 Spyglass can be connected to show traction and steering information such as BDI, hour meter, fault, traction speed, and steered wheel angle.
▶ +5V and +12V low-power supplies for input sensors, etc.
▶ CANopen system communication.
▶ Curtis 1313 handheld programmer and Curtis CSS provide easy programming and powerful system diagnostic and monitoring capabilities.
▶ Status LED on the cover gives instant diagnostic indication.

Maximum Safety

▶ Dual redundant configuration of all safety relevant parts.
▶ Fault output can be used to turn off traction controller’s main contactor and EM Brake.
▶ Separate input paths to each micro for all input and feedback signals.
▶ Following error check ensures the wheel position tracks the steering command.
▶ Power On Self-Test: FLASH, ALU, EEPROM, software watchdog, RAM, etc.
▶ Power On Hardware Check: Motor Open, Motor Short, and MOSFET short.
▶ Periodic Self-Tests: EEPROM parameters, Motor Open and command and feedback devices.

Meets or complies with relevant US and International Regulations

▶ EMC: Designed to the requirements of EN12895:2015.
▶ UL recognized per UL583.
▶ Designed to the EN13849 standard achieving a PL=d, Category 3 for all Safety Functions.
▶ Electronics sealed to IPX4.
▶ Regulatory compliance of the complete vehicle system with the controller installed is the responsibility of the vehicle OEM.
**SYSTEM ACCESSORIES**

**Curtis AC Motor Speed Controllers**
Curtis AC motor speed controllers provide highly efficient control of AC induction motors performing traction drive or hydraulic pump duties, and offer the highest levels of functional safety.

**Curtis Model 840**
The Curtis Model 840 LCD Multifunction display contains 8 large, easy to read characters to provide display of battery discharge (BDI), hour meter and error messages. Built-in backlight is also available.

**Curtis Model 1313**
The Curtis Model 1313 Handheld Programmer is ideal for setting parameters and performing diagnostic functions.

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**MODEL CHART**

<table>
<thead>
<tr>
<th>Model Number</th>
<th>Nominal Battery Voltage (V)</th>
<th>Max Boost Current, 10 Sec (A)</th>
<th>1 Min Current Rating (A)</th>
<th>60 Min Current Rating (A)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1220E-24xx</td>
<td>24</td>
<td>70</td>
<td>60</td>
<td>30</td>
</tr>
<tr>
<td>1220E-54xx</td>
<td>36–48</td>
<td>70</td>
<td>60</td>
<td>30</td>
</tr>
</tbody>
</table>
## Model 1220E

### Dimensions mm

- **Width:** 141.0 mm
- **Height:** 79.0 mm
- **Depth:** 63.0 mm
- **Height:** 25.0 mm
- **Width:** 33.0 mm
- **Height:** 47.5 ± 1.0 mm

### Pinout Chart

#### J1

<table>
<thead>
<tr>
<th>Pin</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Rx</td>
</tr>
<tr>
<td>2</td>
<td>I/O GND</td>
</tr>
<tr>
<td>3</td>
<td>Tx</td>
</tr>
<tr>
<td>4</td>
<td>+12V</td>
</tr>
</tbody>
</table>

#### J2

<table>
<thead>
<tr>
<th>Pin</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Home Switch 2</td>
</tr>
<tr>
<td>2</td>
<td>Interlock Input 2</td>
</tr>
<tr>
<td>3</td>
<td>Command Encoder 2A</td>
</tr>
<tr>
<td>4</td>
<td>Command Encoder 2B</td>
</tr>
<tr>
<td>5</td>
<td>Steer Motor Encoder 2A</td>
</tr>
<tr>
<td>6</td>
<td>Steer Motor Encoder 2B</td>
</tr>
<tr>
<td>7</td>
<td>CAN Term H</td>
</tr>
<tr>
<td>8</td>
<td>Aux Analog Input</td>
</tr>
</tbody>
</table>

#### J3

<table>
<thead>
<tr>
<th>Pin</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Fault Output</td>
</tr>
<tr>
<td>2</td>
<td>Steer Motor Encoder 1A / Position Analog 1</td>
</tr>
<tr>
<td>3</td>
<td>Home Switch 1</td>
</tr>
<tr>
<td>4</td>
<td>Interlock Input 1</td>
</tr>
<tr>
<td>5</td>
<td>KSI</td>
</tr>
<tr>
<td>6</td>
<td>Comm and Analog 1 / Comm and Encoder 1A</td>
</tr>
<tr>
<td>7</td>
<td>+5V Supply 1</td>
</tr>
<tr>
<td>8</td>
<td>CAN H</td>
</tr>
<tr>
<td>9</td>
<td>Steer Motor Encoder 1B / Position Analog 2</td>
</tr>
<tr>
<td>10</td>
<td>I/O GND</td>
</tr>
<tr>
<td>11</td>
<td>+5V Supply 2</td>
</tr>
<tr>
<td>12</td>
<td>CAN L</td>
</tr>
<tr>
<td>13</td>
<td>Comm and Analog 2 / Comm and Encoder 1B</td>
</tr>
<tr>
<td>14</td>
<td>I/O GND</td>
</tr>
</tbody>
</table>
Model 1220E

CONNECTOR WIRING

Relative Position Mode

Interlock Switch

J3-4

J2-2

N.O.

J3-3

N.C.

J2-1

J3-5

Home Switch

Dual Command Encoder

J3-7

J3-6

J3-13

J2-3

J2-4

J3-14

Dual Steer Motor Encoder

J3-11

J3-2

J3-9

J2-5

J2-6

J3-10

J2-8

Interlock Input 1

Interlock Input 2

Home Switch 1

Home Switch 2

KSI

+5V Supply 1

Command Analog 1/Encoder 1A

Command Analog 2/Encoder 1B

Command Encoder 2A

Command Encoder 2B

I/O GND

+5V Supply 2

Steer Motor Encoder 1A/
Position Analog 1

Steer Motor Encoder 1B/
Position Analog 2

Steer Motor Encoder 2A

Steer Motor Encoder 2B

I/O GND

Auxiliary Analog Input

+12V

Tx

I/O GND

Rx

Programmer

CAN TERM H

CAN TERM L

Interlock Input 1

Interlock Input 2

Home Switch 1

Home Switch 2

KSI

+5V Supply 1

Command Analog 1/Encoder 1A

Command Analog 2/Encoder 1B

Command Encoder 2A

Command Encoder 2B

I/O GND

+5V Supply 2

Steer Motor Encoder 1A/
Position Analog 1

Steer Motor Encoder 1B/
Position Analog 2

Steer Motor Encoder 2A

Steer Motor Encoder 2B

I/O GND

Auxiliary Analog Input

+12V

Tx

I/O GND

Rx

Programmer

CAN TERM H

CAN TERM L

Interlock Input 1

Interlock Input 2

Home Switch 1

Home Switch 2

KSI

+5V Supply 1

Command Analog 1/Encoder 1A

Command Analog 2/Encoder 1B

Command Encoder 2A

Command Encoder 2B

I/O GND

+5V Supply 2

Steer Motor Encoder 1A/
Position Analog 1

Steer Motor Encoder 1B/
Position Analog 2

Steer Motor Encoder 2A

Steer Motor Encoder 2B

I/O GND

Auxiliary Analog Input

+5V Supply 1

Command Analog 1/Encoder 1A

Command Analog 2/Encoder 1B

Command Encoder 2A

Command Encoder 2B

I/O GND

+5V Supply 2

Steer Motor Encoder 1A/
Position Analog 1

Steer Motor Encoder 1B/
Position Analog 2

Steer Motor Encoder 2A

Steer Motor Encoder 2B

I/O GND

Auxiliary Analog Input

Programmer

CAN TERM H

CAN TERM L

Connect Jumper for 120Ω CANbus Termination

CAN H

CAN L

Fault Output

Home Switch 2

Home Switch 1

KSI

+5V Supply 1

Command Analog 1/Encoder 1A

Command Analog 2/Encoder 1B

Command Encoder 2A

Command Encoder 2B

I/O GND

+5V Supply 2

Steer Motor Encoder 1A/
Position Analog 1

Steer Motor Encoder 1B/
Position Analog 2

Steer Motor Encoder 2A

Steer Motor Encoder 2B

I/O GND

Auxiliary Analog Input

Power Fuse

Control Fuse

Emergency Stop

Battery

www.curtisinstruments.com
CONNECTOR WIRING

Absolute Position Mode

Model 1220E

Specifications subject to change without notice 50321 REV D 2/19 ©2019 Curtis Instruments, Inc.

WARRANTY
Two year limited warranty from time of delivery.

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